

## Damped oscillations

A harmonic oscillator has no losses, its total energy is constant and the amplitude of the oscillations is the same in the course of the movement. This is a crude approximation. Usually there is friction. The simplest way to take friction into account is to introduce in the equation a term proportional to the velocity. Newton's 2<sup>nd</sup> law writes:

$$m\ddot{x} + \gamma\dot{x} + kx = 0 \quad (\text{O10})$$

with  $\gamma > 0$  a damping factor. (Why positive gammas?). The analogous of Eq. (O1) is:

$$\ddot{x} + \frac{2}{\tau}\dot{x} + \omega_0^2 x = 0 \quad (\text{O11})$$

The notation  $\frac{\gamma}{m} = \frac{2}{\tau}$  simplifies the final relations.

*Question:* What are the MU for  $\tau$  ?

Solve Eq. (O11) by Euler.  $r^2 + \frac{2}{\tau}r + \omega_0^2 = 0$ ,

$$r_{1,2} = -\frac{1}{\tau} \pm \sqrt{\left(\frac{1}{\tau}\right)^2 - \omega_0^2} \quad (\text{O12})$$

Three situations present:

a).  $\frac{1}{\tau} > \omega_0$ . **Both roots are real and both negative.** Depending on initial

conditions the movement is a decay, possibly preceded by an increase.

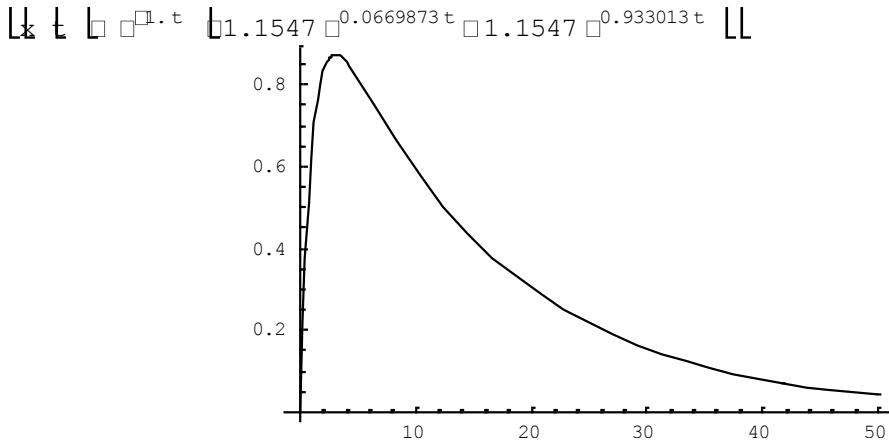
**Assume**  $\tau = 1 s^{-1}$ ,  $\omega_0 = 0.25 s^{-1}$ .

Analytic solution:

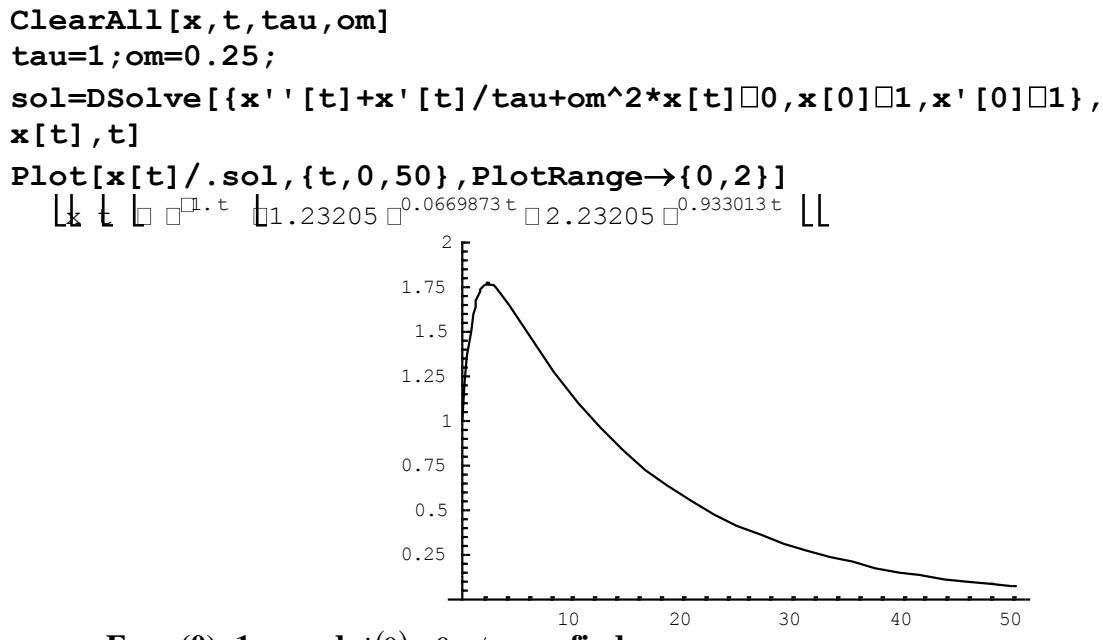
$$x(t) = e^{-t/\tau} \left( A \exp\left[\sqrt{\left(\frac{1}{\tau}\right)^2 - \omega_0^2}\right] + B \exp\left[-\sqrt{\left(\frac{1}{\tau}\right)^2 - \omega_0^2}\right] \right) \quad (\text{O13})$$

**For  $x(0)=0$  and  $\dot{x}(0)=1 m/s$  one finds:**

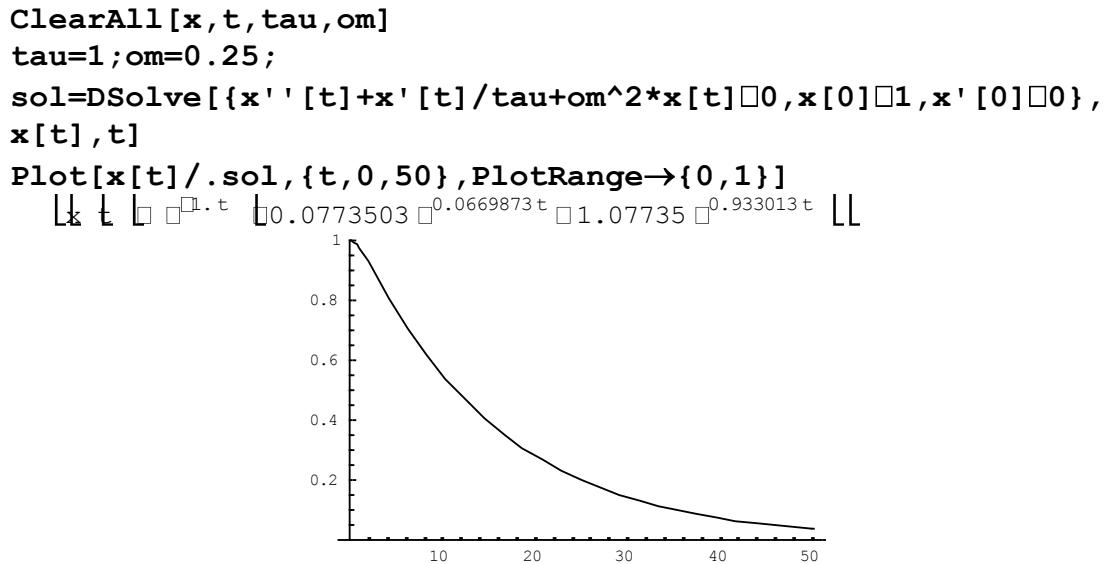
```
ClearAll[x,t,tau,om]
tau=1;om=0.25;
sol=DSolve[{x''[t]+x'[t]/tau+om^2*x[t]==0,x[0]==0,x'[0]==1},
x[t],t]
Plot[x[t]/.sol,{t,0,50},PlotRange->All]
```



For  $x(0)=1$  m and  $\dot{x}(0)=1$  m/s one finds:

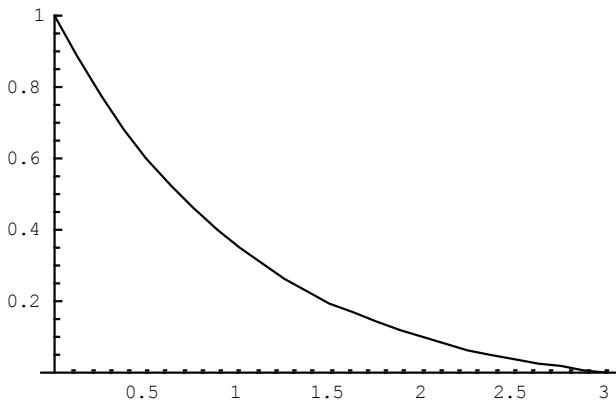


For  $x(0)=1$  m and  $\dot{x}(0)=0$  m/s one finds:



For  $x(0)=1$  m and  $\dot{x}(0)=-1$  m/s one finds:

```
ClearAll[x,t,tau,om]
tau=1;om=0.25;
sol=DSolve[{x''[t]+x'[t]/tau+om^2*x[t]==0,x[0]==1,x'[0]==-1},x[t],t]
Plot[x[t]/.sol,{t,0,3},PlotRange→{0,1}]
```



**Conclusion: The solution essentially depends on the initial conditions (of course, also on the equation and the coefficients).**

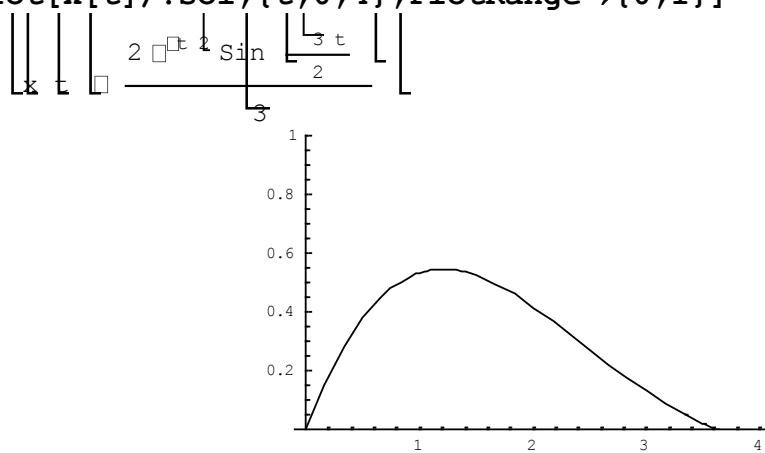
b)  $\frac{1}{\tau} = \omega_0$  (critical damping). Equal roots

Analytic solution:

$$x(t) = (At + B)e^{-t/\tau} \quad (\text{O14})$$

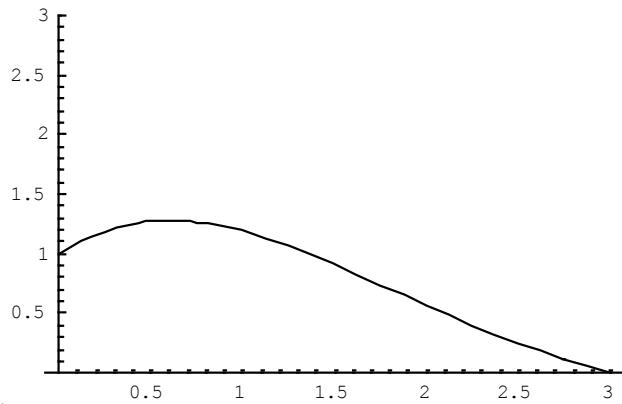
For  $x(0)=0$  and  $\dot{x}(0)=1$  m/s one finds:

```
ClearAll[x,t,tau,om]
tau=1;om=1;
sol=DSolve[{x''[t]+x'[t]/tau+om^2*x[t]==0,x[0]==0,x'[0]==1},x[t],t]
Plot[x[t]/.sol,{t,0,4},PlotRange→{0,1}]
```



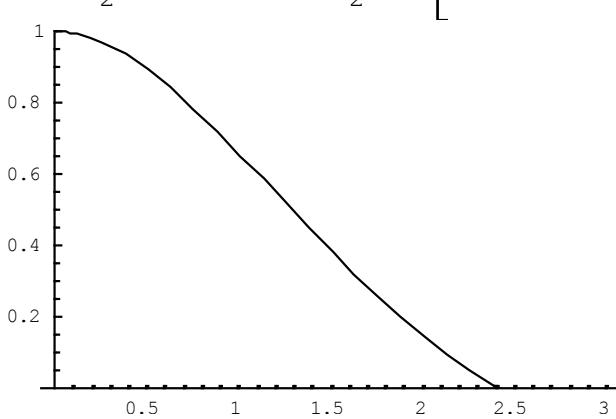
For  $x(0)=1$  m and  $\dot{x}(0)=1$  m/s one finds:

```
ClearAll[x,t,tau,om]
tau=1;om=1;
sol=DSolve[{x''[t]+x'[t]/tau+om^2*x[t]==0,x[0]==1,x'[0]==1},
x[t],t]
Plot[x[t]/.sol,{t,0,3},PlotRange→{0,3}]
```



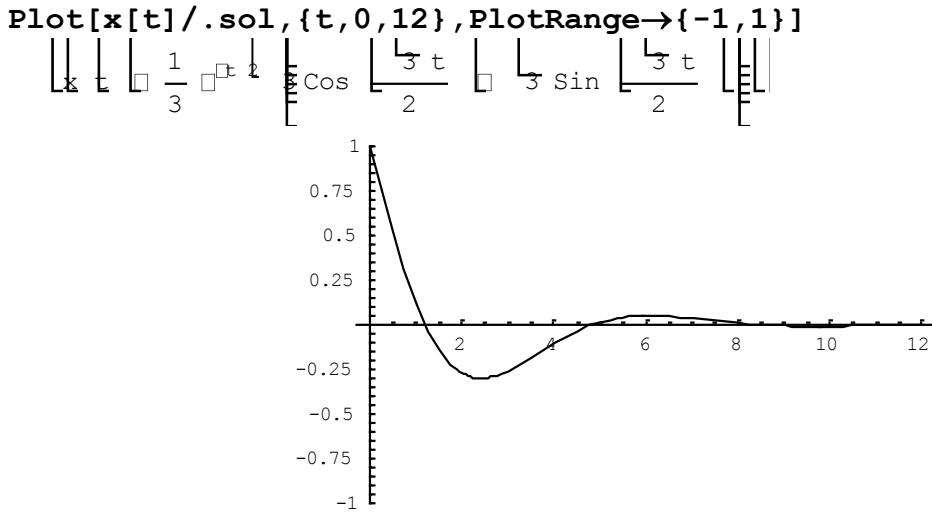
For  $x(0)=1$  m and  $\dot{x}(0)=0$  m/s one finds:

```
ClearAll[x,t,tau,om]
tau=1;om=1;
sol=DSolve[{x''[t]+x'[t]/tau+om^2*x[t]==0,x[0]==1,x'[0]==0},
x[t],t]
Plot[x[t]/.sol,{t,0,3},PlotRange→{0,1}]
```



For  $x(0)=1$  m and  $\dot{x}(0)=-1$  m/s one finds:

```
ClearAll[x,t,tau,om]
tau=1;om=1;
sol=DSolve[{x''[t]+x'[t]/tau+om^2*x[t]==0,x[0]==1,x'[0]==-1},
x[t],t]
```



c)  $\frac{1}{\tau} < \omega_0$  small damping, complex conjugated roots

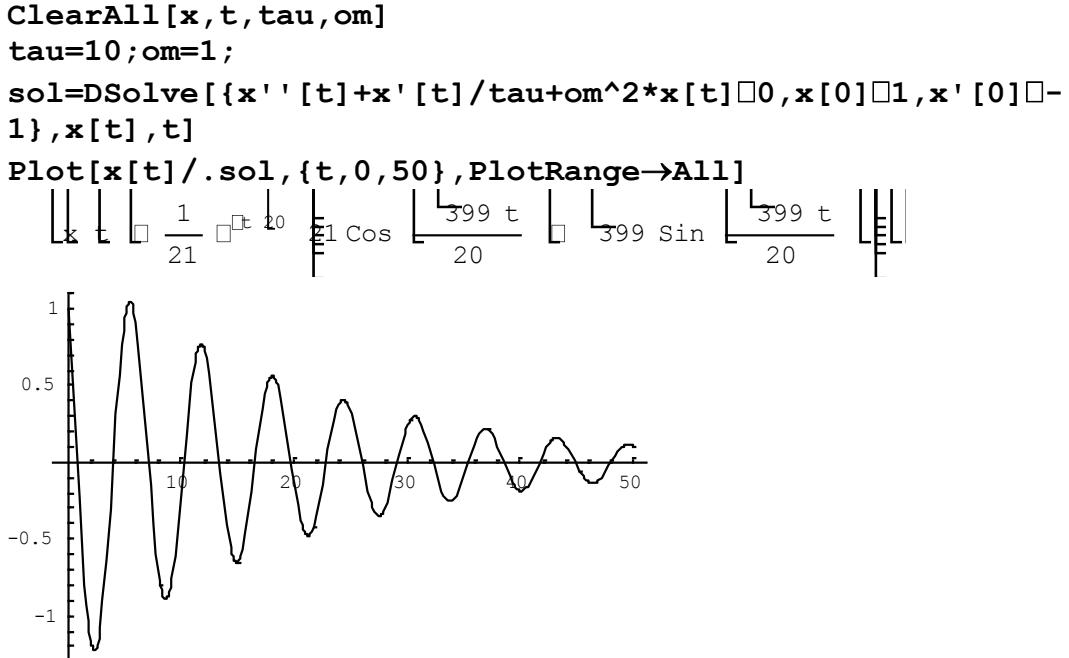
**Analytic solution:**

$$x(t) = e^{-t/\tau} (A \sin(\omega t) + B \cos(\omega t)) = C e^{-t/\tau} \sin(\omega t + \varphi_0) \quad (\text{O15})$$

with the effective angular frequency

$$\omega = \sqrt{\omega_0^2 - \left(\frac{1}{\tau}\right)^2} \quad (\text{O16})$$

**For  $x(0)=0$  and  $\dot{x}(0)=1 \text{ m/s}$  (and for other conditions as well) one finds:**



This is the most important situation: the point oscillates, but with diminishing amplitude. The movement is not perfectly periodic, but only *quasi-periodic*, with a *quasi-period* defined as:

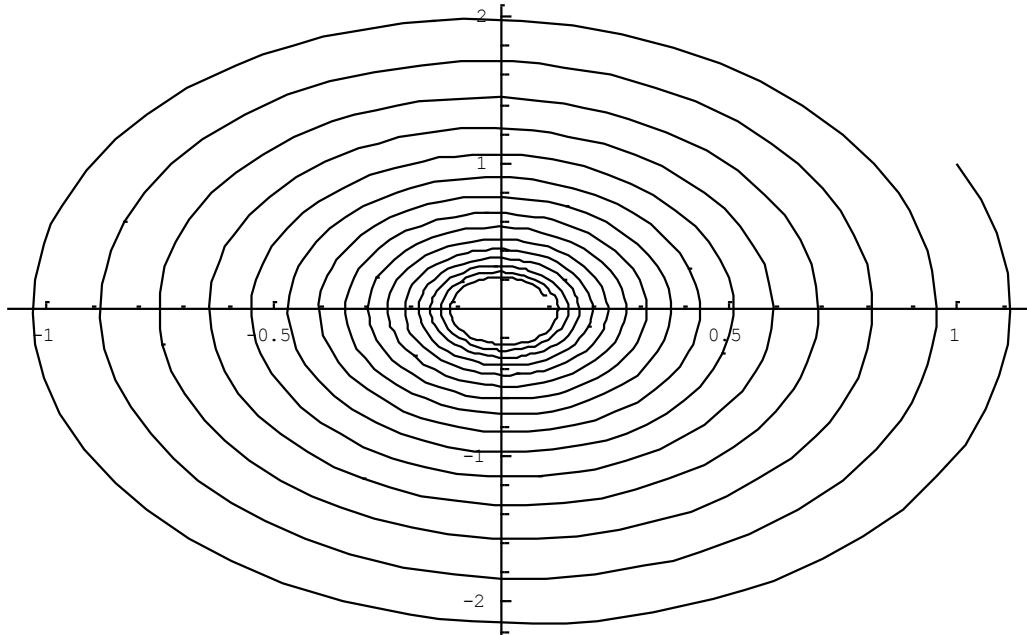
$$T = \frac{2\pi}{\omega} = \frac{2\pi}{\sqrt{\omega_0^2 - \left(\frac{1}{\tau}\right)^2}} \quad (\text{O17})$$

*The logarithmic decrement* is defined by:

$$\delta = \ln \frac{x(t)}{x(t+T)} = \frac{T}{\tau} \quad (\text{O18})$$

An attenuated oscillator in phase space goes inward:

```
ParametricPlot[{xsol[t], xsol'[t]}, {t, 0, 15*Pi}]
```



*Question:* What would represent a spiral going outward ?