## D.2. Energetic quantities: kinetic energy, work, total energy

*Force is the agent of change, energy is the measure of the change* (E. Hecht, Physics, Algebra/Trig, Ch. 6, Energy).

**Work** is the amount of energy transmitted by a force acting along a certain distance. If the force is constant work is easily defined as follows.

One body. 1D situation: Along a straight line:

$$W = \pm F \cdot x \tag{D4}$$

If W>0 work is done by the force, if W<0 work is done against the force.

*3D case*. Definition for one body:

$$W = \vec{F} \cdot \vec{r} = F r \cos \alpha \tag{D4'}$$

It may be >0, <0, or =0.

For *n* bodies work is just the sum of expressions of the type (D4) or (D4').

If the force varies one has to consider a small displacement dx and write in 1D case:

$$\delta W = F dx$$
, hence  $W = \int_{(1)}^{(2)} F dx$  (D5)

In the 3D case however, one may still write the elementary work as

$$\delta W = \vec{F} \cdot d\vec{r} = F_x dx + F_y dy + F_z dz$$
(D6)

 $\delta W$  is not the differential of some function, it is just an elementary work, computed for a small distance dx or  $d\vec{r}$ .

Functions of several variables !! Partial derivatives !!

And how could we figure out the integral:

$$W = \int_{(1)}^{(2)} (F_x dx + F_y dy + F_z dz)$$
 (D6')

Line integral or path integral !!

**Kinetic energy.** By definition kinetic energy of a body of mass *m* moving with velocity  $\vec{v}$  is given by:

$$E_k = \frac{m\vec{v}^2}{2} = \frac{\vec{p}^2}{2m} \quad (\text{we have used } \vec{p} = m\vec{v}) \tag{D7}$$

Question: what reference frame did we use ?

For *n* material points with masses  $m_i$  the definition is:

$$E_k = \sum_{i=1}^n \frac{m_i \vec{v}_i^2}{2} = \sum_{i=1}^n \frac{\vec{p}_i^2}{2m_i}$$
(D8)

*Remark:* the factor 1/2 will become clear later.

## Variation of the kinetic energy.

$$\Delta E_k = W_{12} \tag{D9}$$

with  $W_{12}$  the total work made by *all* forces, internal and external, during the movement from (1) to (2).

Demonstration for 1 body.  $E_k = \frac{m\vec{v}^2}{2}$ ,  $dE_k = \vec{v} \cdot md\vec{v} = \vec{v} \cdot d\vec{p} = \frac{d\vec{r}}{dt} \cdot d\vec{p} = \frac{d\vec{p}}{dt} \cdot d\vec{r} = \vec{F} \cdot d\vec{r} = \delta W$  (D10)  $\Delta E_k = \int_{1}^{2} \delta W = W_{12}$ . Try to demonstrate the same relation for n bodies. Faceti va rog demonstartia asta

*Remark.* In (D9)  $W_{12}$  is the work on the path from the point (1) to the point (2). In 2D or 3D this work depends in general on the actual pathway. In the particular case when work does not depend on the actual path, one says the force is conservative, or that the force is given by a potential. Then and only then the elementary work  $\delta W$  becomes a usual differential.

**Conservative forces.** If forces are conservative,  $\delta W = -dU$ , with dU the potential energy of the system. Introducing in (D9):

$$dE_k + dU = d(E_k + U) = dE_{tot} = 0, \quad \text{or} \qquad E_{tot} = const \tag{D11}$$

*Examples:* gravitational field, elastic field, but *not* problems with friction. For the elastic field 1D

$$U = \frac{kx^2}{2} \qquad F = -\frac{dU}{dx} = -kx \qquad (D12)$$
  
In 3D 
$$U = \frac{k\vec{r}^2}{2} \text{ and } \vec{F} = -k\vec{r}.$$